

Full Length Research Paper

## Application of $\exp(-\phi(\xi))$ - expansion method to find the exact solutions of Sharma-Tasso-Olver Equation

Nizhum Rahman<sup>1</sup>, Md. Nur Alam<sup>1</sup>, Harun-Or-Roshid<sup>1\*</sup>, Selina Akter<sup>1</sup> and M. Ali Akbar<sup>2</sup>

<sup>1</sup>Department of Mathematics, Pabna University of Science and Technology, Bangladesh.

<sup>2</sup>Department of Applied Mathematics, University of Rajshahi, Bangladesh.

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In this work, we present traveling wave solutions for the Sharma-Tasso-Olver equation. The idea of  $\exp(-\phi(\xi))$ -expansion method is used to obtain exact solutions of that equation. The traveling wave solutions are expressed by the exponential functions, the hyperbolic functions, the trigonometric functions solutions and the rational functions. It is shown that the method is awfully effective and can be used for many other nonlinear evolution equations (NLEEs) in mathematical science and engineering.

**Key words:** The  $\exp(-\phi(\xi))$ -expansion method, the Sharma-Tasso-Olver equation, nonlinear partial differential equation, homogeneous balance, traveling wave solutions, solitary wave solutions.

### INTRODUCTION

The study of nonlinear evolution equation (NLEE) has much remarkable progress in the past few decades. Most of the phenomena in real world can be described using non-linear equations. A nonlinear phenomenon plays a vital role in applied mathematics, physics and engineering branches. Most of the complex nonlinear equations in plasma physics, fluid dynamics, chemistry, biology, mechanics, elastic media and optical fibers etc., can be explained by nonlinear evolution equations. There are a lot of NLEEs that are integrated using various mathematical techniques.

In recent times, many powerful and effective methods have been presented such as the Ansatz method (Hu, 2001a,b; Wang et al., 2013), the Complex hyperbolic function method (Zayed et al., 2006; Chow, 1995), the  $(G'/G)$ -expansion method (Wang et al., 2008; Alam et al., 2014; Alam and Akbar, 2013; Alam et al., 2013; Bekir, 2008; Roshid et al., 2013a,b; Neyrame et al., 2012; Akbar et al., 2012), the F-expansion method (Wang and

Zhou, 2003; Wang and Zhou, 2005), the Backlund transformation method (Miura, 1978), the Darboux transformation method (Matveev and Salle, 1991), the Homogeneous balance method (Wang, 1995, 1996; Zayed et al., 2004), the Adomian decomposition method (Adomian, 1994; Wazwaz, 2002), the Auxiliary equation method (Sirendaoreji, 2003, 2007), the Simplest equation (Eslami et al., 2013; Yildirim et al., 2012) and so on.

Recently, Wang and Xu (2013a,b) and Wang et al. (2014), presented some exact solutions of different nonlinear evolution equations by Lie group analysis. Wang and Xu (2013a) established exact solutions of nonlinear time fractional Sharma-Tasso-Olver equation via Lie group analysis. Zhao and Li (2013) proposed the  $\exp(-\phi(\eta))$ -expansion method to find new type of solutions for nonlinear evolution equations. In this work, we apply  $\exp(-\phi(\xi))$ -expansion method to solve the Sharma-Tasso-Olver equation.

\*Corresponding author. E-mail: harunoroshidmd@gmail.com

**METHODOLOGY**

In this section we describe  $\exp(-\phi(\xi))$ - expansion method for finding traveling wave solutions of nonlinear evolution equations (Miura, 1978). Suppose that a nonlinear equation, say in two independent variables  $x$  and  $t$  is given by:

$$F(u, u_t, u_x, u_{tt}, u_{xx}, u_{xt}, \dots) = 0 \tag{1}$$

where  $u(\xi) = u(x, t)$  is an unknown function,  $F$  is a polynomial of  $u(x, t)$  and its partial derivatives in which the highest order derivatives and nonlinear terms are involved. In the following, we give the main steps of this method:

**Step 1**

Combining the independent variables  $x$  and  $t$  into one variable  $\xi = x \pm \omega t$ , we suppose that

$$u(x, t) = u(\xi), \quad \xi = x \pm \omega t \tag{2}$$

The travelling wave transformation Equation (2) permits us to reduce Equation (1) to the following ordinary differential equation (ODE):

$$\mathfrak{R}(u, u', u'', \dots) = 0 \tag{3}$$

where  $\mathfrak{R}$  is a polynomial in  $u(\xi)$  and its derivatives,

$$u'(\xi) = \frac{du}{d\xi}, \quad u''(\xi) = \frac{d^2u}{d\xi^2} \text{ and so on.}$$

**Step 2**

We suppose that Equation (3) has the formal solution:

$$u(\xi) = \sum_{i=0}^n A_i (\exp(-\phi(\xi)))^i \tag{4}$$

Where  $A_i (0 \leq i \leq n)$  are constants to be determined, such that  $A_n \neq 0$  and  $\phi = \phi(\xi)$  satisfies the following ODE:

$$\phi'(\xi) = \exp(-\phi(\xi)) + \mu \exp(\phi(\xi)) + \lambda \tag{5}$$

Equation (5) gives the following solutions:

When  $\lambda^2 - 4\mu > 0, \mu \neq 0$ ,

$$\phi(\xi) = \ln\left(\frac{-\sqrt{(\lambda^2 - 4\mu)} \tanh\left(\frac{\sqrt{(\lambda^2 - 4\mu)}}{2}(\xi + E)\right) - \lambda}{2\mu}\right) \tag{6}$$

When  $\lambda^2 - 4\mu < 0, \mu \neq 0$ ,

$$\phi(\xi) = \ln\left(\frac{\sqrt{(4\mu - \lambda^2)} \tan\left(\frac{\sqrt{(4\mu - \lambda^2)}}{2}(\xi + E)\right) - \lambda}{2\mu}\right) \tag{7}$$

When  $\lambda^2 - 4\mu > 0, \mu = 0, \lambda \neq 0$ ,

$$\phi(\xi) = -\ln\left(\frac{\lambda}{\exp(\lambda(\xi + E)) - 1}\right) \tag{8}$$

When  $\lambda^2 - 4\mu = 0, \mu \neq 0, \lambda \neq 0$ ,

$$\phi(\xi) = \ln\left(-\frac{2(\lambda(\xi + E) + 2)}{\lambda^2(\xi + E) - 1}\right) \tag{9}$$

When  $\lambda^2 - 4\mu = 0, \mu = 0, \lambda = 0, \phi(\xi) = \ln(\xi + E)$  \tag{10}

$A_n, \dots, \omega, \lambda, \mu$  are constants to be determined later,  $A_n \neq 0$ , the positive integer  $n$  can be determined by considering the homogeneous balance between the highest order derivatives and the nonlinear terms appearing in Equation (3).

**Step 3**

We substitute Equation (4) into Equation (3) and then we account the function  $\exp(-\phi(\xi))$ . As a result of this substitution, we get a polynomial of  $\exp(-\phi(\xi))$ . We equate all the coefficients of same power of  $\exp(-\phi(\xi))$  to zero. This procedure yields a system of algebraic equations whichever can be solved to find  $A_N, \dots, V, \lambda, \mu$ . Substituting the values of  $A_N, \dots, V, \lambda, \mu$  into Equation (4) along with general solutions of Equation (5) completes the determination of the solution of Equation (1).

**Application of the method**

Here we will present the  $\exp(-\phi(\xi))$  expansion method to

construct the exact solutions and then the solitary wave solutions of the Shorma-Tasso-Olver equation. First consider the Shorma-Tasso-Olver equation in the forms:

$$u_t + a(u^3)_x + \frac{3}{2}a(u^2)_{xx} + au_{xxx} = 0 \tag{11}$$

Using the wave transformation  $u(x,t) = u(\xi)$ ,  $\xi = x - vt$  Equation (12) is carried to an ODE

$$-vu' + a(u^3)' + \frac{3}{2}a(u^2)'' + au''' = 0 \tag{12}$$

Equation (12) is integrable, therefore, integrating with respect to  $\xi$  once yields:

$$C - vu + au^3 + \frac{3}{2}a(u^2)' + au'' = 0 \tag{13}$$

Now, balancing the highest order derivative  $u''$  and non-linear term  $u^3$ , we get  $n = 1$ . Therefore, the solution of Equation (13) is of the form:

$$u(\xi) = A_0 + A_1(\exp(-\Phi(\xi))), \tag{14}$$

where  $A_0, A_1$  are constants to be determined such that  $A_N \neq 0$ , while  $\lambda, \mu$  are arbitrary constants.

Substituting Equation (14) into Equation (13) and then equating the coefficients of  $\exp(-\phi(\xi))$  to zero, we get:

$$-3aA_1A_0\mu - VA_0 + aA_1\lambda + aA_0^3 + P = 0 \tag{15}$$

$$2aA_1\mu + 3aA_0^2A_1 - 3aA_0A_1\lambda - VA_1 - 3aA_1^2\mu + aA_1\lambda = 0 \tag{16}$$

$$3aA_1\lambda - 3aA_0A_1 - 3aA_1A_0 - 3aA_1^2\lambda + 3aA_0A_1^2 = 0 \tag{17}$$

$$2aA_1 + aA_1^3 - 3aA_1^2 = 0 \tag{18}$$

Solving the Equation (15) - Equation (18), yields:

**Case 1**

$$P = 2aA_0\mu + 2aA_0^3 - 3aA_0^2\lambda + aA_0\lambda^2 - a\mu\lambda$$

$$V = -a\mu + 3aA_0^2 - 3aA_0\lambda + a\lambda^2, A_0 = A_0, A = 1$$

**Case 2**

$$V = -4a\mu + a\lambda^2, A_0 = \lambda, A_1 = 2$$

For Case 1:

Now substituting the values of  $V, A_0, A_1$  into Equation (14) yields

$$u(\xi) = A_0 + \exp(-\phi(\xi)), \tag{19}$$

where  $\xi = x + a(\mu - 3A_0^2 + 3A_0\lambda - \lambda^2)t$

Now substituting Equation (6) - Equation (10) into Equation (19) respectively, we get the following five traveling wave solutions of modified equal width equation.

When  $\mu \neq 0, \lambda^2 - 4\mu > 0,$

$$u_1(\xi) = A_0 - \left( \frac{2\mu}{\sqrt{\lambda^2 - 4\mu} \tanh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}(\eta + E)\right) + \lambda} \right)$$

where  $\xi = x + a(\mu - 3A_0^2 + 3A_0\lambda - \lambda^2)t$ ,  $E$  is an arbitrary constant.

When  $\mu \neq 0, \lambda^2 - 4\mu < 0,$

$$u_2(\xi) = A_0 + \left( \frac{2\mu}{\sqrt{(4\mu - \lambda^2)} \tan\left(\frac{\sqrt{(4\mu - \lambda^2)}}{2}(\xi + E)\right) - \lambda} \right)$$

where  $\xi = x + a(\mu - 3A_0^2 + 3A_0\lambda - \lambda^2)t$ ,  $E$  is an arbitrary constant.

When  $\mu = 0, \lambda \neq 0,$  and  $\lambda^2 - 4\mu > 0,$

$$u_3(\xi) = A_0 + \frac{\lambda}{\exp(\lambda(\xi + E)) - 1}$$

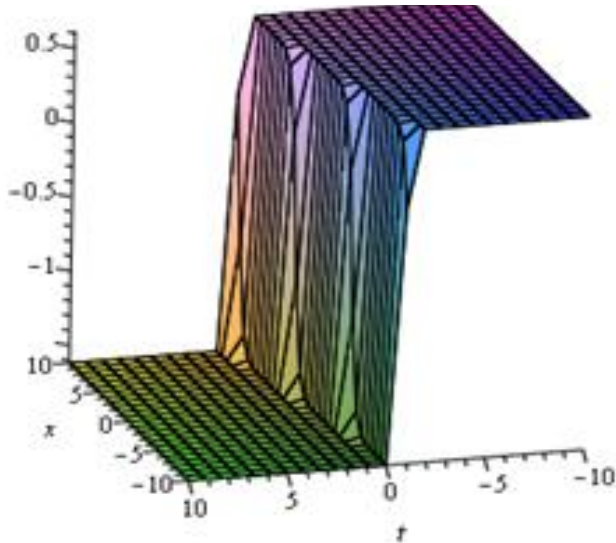
where  $\xi = x + a(-3A_0^2 + 3A_0\lambda - \lambda^2)t$ ,  $E$  is an arbitrary constant.

When  $\mu \neq 0, \lambda \neq 0,$  and  $\lambda^2 - 4\mu = 0,$

$$u_4(\xi) = A_0 - \frac{\lambda^2(\xi + E) - 1}{2(\lambda(\xi + E) + 2)}$$

where  $\xi = x + a(\mu - 3A_0^2 + 3A_0\lambda - \lambda^2)t$ ,  $E$  is an arbitrary constant.

When  $\mu = 0, \lambda = 0,$  and  $\lambda^2 - 4\mu = 0,$   $u_5(\xi) = A_0 + \frac{1}{\xi + E}$



**Figure 1.** Kink solution of  $u_1$  with  $A_0 = 1, A_1 = 1, a = 4, \lambda = 3, \mu = 1, E = 3$  and  $-10 \leq x, t \leq 10$ .

where  $\xi = x + a(\mu - 3A_0^2 + 3A_0\lambda - \lambda^2)t$ ,  $E$  is an arbitrary constant.

For Case 2:

Now substituting the values of  $V, A_0, A_1$  into Equation (14) yields

$$u(\xi) = \lambda + 2 \exp(-\phi(\xi)), \tag{20}$$

where  $\xi = x + a(\lambda^2 - 4\mu)t$

Now substituting Equation (6) - Equation (10) into Equation (20) respectively, we get the following five traveling wave solutions of modified equal width equation.

When  $\mu \neq 0, \lambda^2 - 4\mu > 0$ ,

$$u_6(\xi) = \lambda - \left( \frac{4\mu}{\sqrt{\lambda^2 - 4\mu} \tanh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}(\eta + E)\right) + \lambda} \right)$$

where  $\xi = x + a(\lambda^2 - 4\mu)t$ ,  $E$  is an arbitrary constant.

When  $\mu \neq 0, \lambda^2 - 4\mu < 0$ ,

$$u_7(\xi) = \lambda + \left( \frac{4\mu}{\sqrt{(4\mu - \lambda^2)} \tan\left(\frac{\sqrt{(4\mu - \lambda^2)}}{2}(\xi + E)\right) - \lambda} \right)$$

where  $\xi = x + a(\lambda^2 - 4\mu)t$ ,  $E$  is an arbitrary constant

When  $\mu = 0, \lambda \neq 0$ , and  $\lambda^2 - 4\mu > 0$ ,

$$u_8(\xi) = \lambda \left( 1 + \frac{2}{\exp(\lambda(\xi + E)) - 1} \right)$$

where  $\xi = x + a\lambda^2 t$ ,  $E$  is an arbitrary constant

When  $\mu \neq 0, \lambda \neq 0$ , and  $\lambda^2 - 4\mu = 0$ ,

$$u_9(\xi) = \lambda - \frac{\lambda^2(\xi + E) - 1}{(\lambda(\xi + E) + 2)}$$

where  $\xi = x$ ,  $E$  is an arbitrary constant

When  $\mu = 0, \lambda = 0$ , and  $\lambda^2 - 4\mu = 0$ ,  $u_{10}(\xi) = \lambda + \frac{2}{\xi + E}$

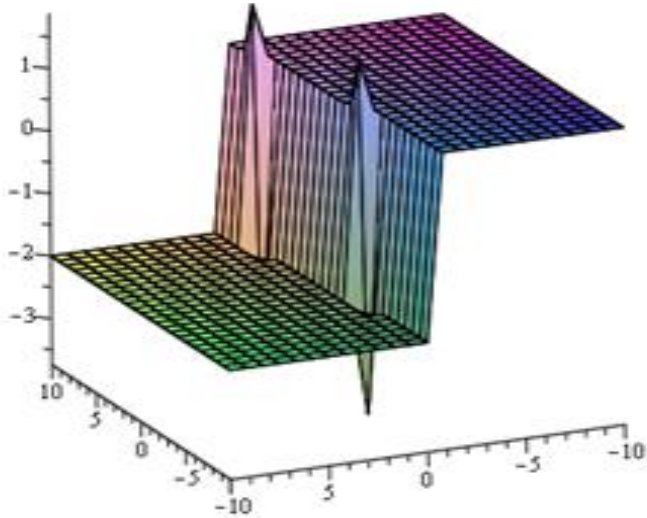
where  $\xi = x$ ,  $E$  is an arbitrary constant.

### GRAPHICAL REPRESENTATION

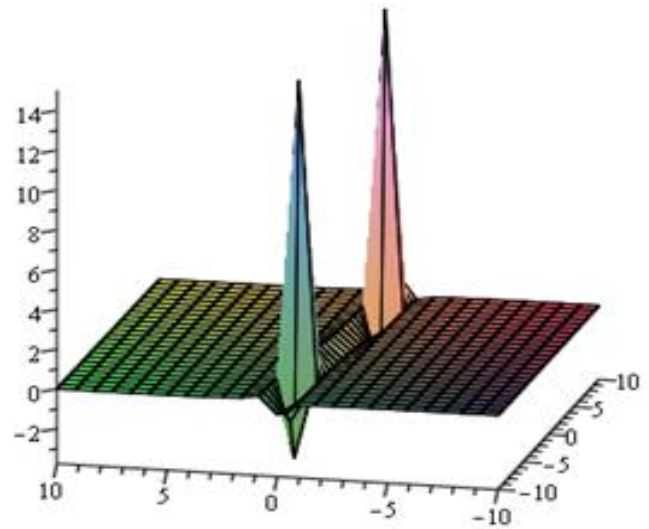
The graphical demonstrations of obtained solutions for particular values of the arbitrary constants are shown in Figure 1 to 5 with the aid of commercial software Maple 13.

### Conclusion

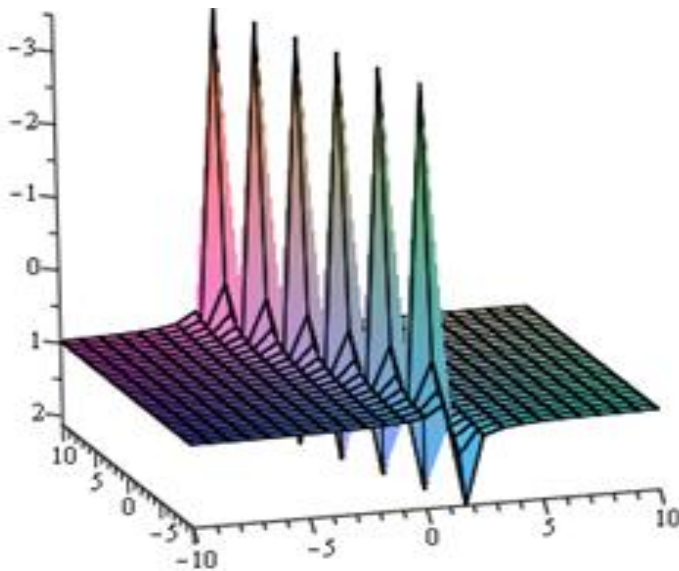
In this paper, we have applied the  $\exp(-\phi(\xi))$ -expansion method for the exact solution of the Shorma-Tasso-Olver equation and constructed some new exact travelling wave solutions. The travelling wave solutions are expressed by the hyperbolic functions, the trigonometric functions solutions and the rational functions. This paper shows that the  $\exp(-\Phi(\eta))$ -expansion method is quite efficient and effective to find



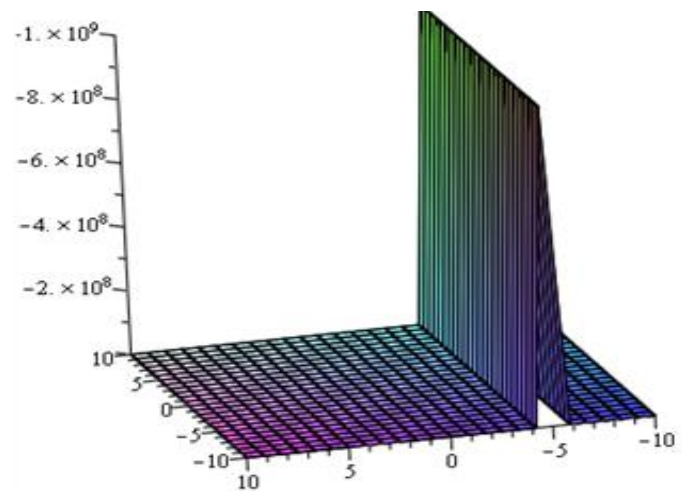
**Figure 2.** Singular Kink of  $u_3$  with  $A_0 = 1, A_1 = 1, a = 4, \lambda = 3, \mu = 1, E = 3$  and  $-10 \leq x, t \leq 10$ .



**Figure 4.** Singular kink of  $u_9(\xi)$  when  $A_0 = \lambda, A_1 = 2, a = 4, \lambda = 2, \mu = 2, E = 5$  and  $-10 \leq x, t \leq 10$ .



**Figure 3.** Singular soliton of  $u_4$  when  $A_0 = 1, A_1 = 1, a = 4, \lambda = 3, \mu = 1, E = 3$  and  $-10 \leq x, t \leq 10$ .



**Figure 5.** Singular soliton of  $u_{10}(\xi)$  when  $A_0 = \lambda, A_1 = 2, a = 4, \lambda = 0, \mu = 0, E = 5$  and  $-10 \leq x, t \leq 10$ .

the exact solutions of NLEEs. Also, we observe that this method can be also applied to other nonlinear evolution equations.

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